

# MMAAT 5011 Analysis II

## Review of linear algebra

Defn A vector space  $V$  over a field  $F$

is a set with two operations:

addition:  $+ : V \times V \rightarrow V$

scalar multiplication:  $\cdot : F \times V \rightarrow V$  such that

1.  $x + y = y + x$  for all  $x, y \in V$

2.  $(x + y) + z = x + (y + z) \quad \forall x, y, z \in V$

3.  $\exists$  an element  $\vec{0} \in V$  such that  $x + \vec{0} = x \quad \forall x \in V$

5. For any  $x \in V$ ,  $1 \cdot x = x \quad \forall x \in V$

4. For any  $x \in V$ ,  $\exists y \in V$  such that  $x + y = \vec{0}$

We call  $y = -x$

6.  $(\alpha\beta)x = \alpha(\beta x) \quad \forall \alpha, \beta \in F \text{ and } x \in V$

7.  $\alpha(x + y) = \alpha x + \alpha y \quad \alpha \in F, x, y \in V$

8.  $(\alpha + \beta)x = \alpha x + \beta x \quad \alpha, \beta \in F, x \in V$

Rmk ①  $F$  is a field, something you can do  $+$ ,  $-$ ,  $\times$ ,  $\div$  with nice properties

eg  $\mathbb{R}$ ,  $\mathbb{C}$ ,  $\mathbb{Q}$ ,  ~~$\mathbb{Z}$~~   
↑ ↑  
Our focus      no division

② Any vector space /  $\mathbb{C}$  is also a vector space /  $\mathbb{R}$

## Example of vector spaces $V/\mathbb{F}$

①  $\mathbb{R}^n/\mathbb{R}$     $\mathbb{C}^n/\mathbb{C}$     $\mathbb{C}^n/\mathbb{R}$

$\dim = n$     $\dim = n$     $\dim = 2n$

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} + \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 4 \\ 6 \end{bmatrix}$$

$$i \begin{bmatrix} 1 \\ 0 \\ i \end{bmatrix} = \begin{bmatrix} i \\ 0 \\ -1 \end{bmatrix}$$

②  $M_{m \times n}(\mathbb{R})$  = vector space of all  $m \times n$  matrices with real entries

$\dim = mn$

$$2 \times 3 \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} + \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 3 & 4 \\ 5 & 6 & 7 \end{bmatrix}$$

$$(-1) \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} = \begin{bmatrix} -1 & -2 & -3 \\ -4 & -5 & -6 \end{bmatrix}$$

③  $P_n(\mathbb{F})$  = the vector space of all polynomials with coefficients in  $\mathbb{F}$  and degree  $\leq n$

$$x^2 + ix - 7 \in P_4(\mathbb{C})$$

$$\dim P_n(\mathbb{F}) = n + 1$$

$P(\mathbb{F})$  = the vector space of all polynomials with coefficients in  $\mathbb{F}$

$$\dim P(\mathbb{F}) = \infty \text{ (countable)}$$

$P(\mathbb{F})$  has basis  $\{1, x, x^2, x^3, x^4, \dots\}$

④  $C[a, b]$  = vector space of all continuous, real-valued functions defined on  $[a, b]$

$$\dim C[a, b] = \infty \text{ (uncountable)}$$

# Vector subspace

Defn  $V$  is a vector space /  $\mathbb{F}$

A subset  $W \subseteq V$  is called a vector subspace

if

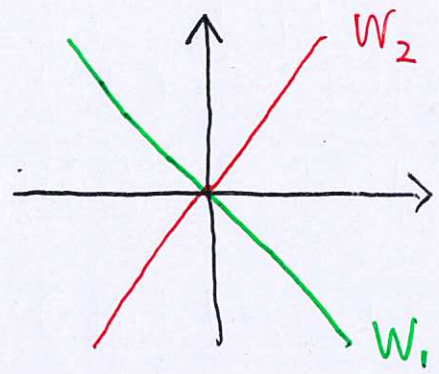
- ①  $\vec{0} \in W$
- ②  $x+y \in W$  if  $x, y \in W$  closed under addition
- ③  $\alpha x \in W$  if  $\alpha \in \mathbb{F}, x \in W$  closed under scalar multiplication

Rmk A vector subspace is a vector space itself with same addition and scalar multiplication

eg 1  $\{(x, y, 0) : x, y \in \mathbb{R}\} \subseteq \mathbb{R}^3$   
 is a vector subspace of  $\mathbb{R}^3$

eg 2  $P(\mathbb{R}) \subseteq P(\mathbb{C}) \supseteq P_n(\mathbb{C})$   
↑ vector subspace over  $\mathbb{R}$       ↑ vector subspace over  $\mathbb{R}$  or  $\mathbb{C}$

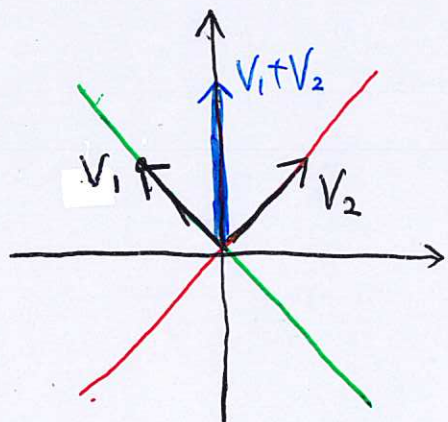
eg 3 let  $V = \mathbb{R}^2$   
 $W_1 = \{(x, y) : x+y=0\}$   
 $W_2 = \{(x, y) : x-y=0\}$        $\{0\}$



$W_1, W_2, W_1 \cap W_2$   
 are vector subspace of  $V$

Q Is  $W_1 \cup W_2$  a vector subspace of  $V$ ?

Ans No



$$V_1 = (-1, 1) \in W_1$$

$$V_2 = (1, 1) \in W_2$$

$$\Rightarrow V_1, V_2 \in W_1 \cup W_2 \quad \swarrow 0+2 \neq 0$$

$$V_1 + V_2 = (0, 2) \notin W_1 \cup W_2$$

$$\Rightarrow V_1 + V_2 \notin W_1 \cup W_2 \quad \swarrow 0-2 \neq 0$$

$W_1 \cup W_2$  fails (2) in defn of vector subspace

$\Rightarrow W_1 \cup W_2$  is not a vector subspace

Q Let  $W_1, W_2$  are vector subspaces of  $V$

Show that  $W_1 \cap W_2$  is a vector subspace of  $V$

Sol

①.  $W_1$  is a vector subspace of  $V \Rightarrow \vec{0} \in W_1$

$W_2$  is " " " "  $\Rightarrow \vec{0} \in W_2$

$$\Rightarrow 0 \in W_1 \cap W_2$$

② Let  $x, y \in W_1 \cap W_2$

$$\therefore x, y \in W_1$$

$W_1$  is a vector subspace  $\Rightarrow x+y \in W_1$

Similarly,  $x+y \in W_2$

$$\Rightarrow x+y \in W_1 \cap W_2$$

③ Let  $x \in W_1 \cap W_2$ ,  $\alpha \in \mathbb{F}$

Then  $x \in W_1$

$W_1$  is a vector subspace

$\Rightarrow \alpha x \in W_1$

Similarly  $\alpha x \in W_2$

$\Rightarrow \alpha x \in W_1 \cap W_2$

We proved  $W_1 \cap W_2$  satisfies

①, ②, ③

$\therefore W_1 \cap W_2$  is a vector subspace of  $V$

## Basis and dimension

Def Let  $V$  be a vector space over  $\mathbb{F}$ ,  $S \subseteq V$  be a subset

① Span  $S \triangleq \left\{ \alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_n x_n : n \geq 0, x_1, x_2, \dots, x_n \in S, \alpha_1, \alpha_2, \dots, \alpha_n \in \mathbb{F} \right\}$

= the set of all linear combinations of  $S$

Note that  $\text{Span } S$  is a vector subspace of  $V$ .

②  $S$  is linearly dependent if there exist

pairwisely distinct  $x_1, x_2, \dots, x_n \in S$  and  $a_1, a_2, \dots, a_n \in \mathbb{F}$ , not all zero

such that  $a_1 x_1 + a_2 x_2 + \dots + a_n x_n = \vec{0}$

$S$  is said to be linearly independent if  $S$  is not linearly dependent

③  $S$  is said to be a basis

(Hamel basis) of  $V$  if

$S$  is linearly independent and

$$\text{Span } S = V$$

Most important feature of a basis:

If  $S$  is a basis of  $V$ , then any

$x \in V$  can be expressed as

$$x = \alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_n x_n$$

with  $x_1, x_2, \dots, x_n \in S$ , pairwise distinct

and  $\alpha_1, \alpha_2, \dots, \alpha_n \in \mathbb{F}$

in a unique way

$\text{Span } S = V \Rightarrow \text{can, l.n. indept} \Rightarrow \text{unique}$

eg 1

Let  $V = \mathbb{R}^3$ ,  $S = \{e_1, e_2, e_3\}$  is a basis,  $e_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $e_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ ,  $e_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

$$\begin{bmatrix} 3 \\ 1 \\ -7 \end{bmatrix} = (3) \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + (1) \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + (-7) \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

or any other vector in  $\mathbb{R}^3$

unique, no other choices

Another basis =  $\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 3000 \end{bmatrix} \right\}$

In general, standard basis of  $\mathbb{R}^n$  is

$\{e_1, e_2, \dots, e_n\}$

⑥

eg 2

$V = P_4(\mathbb{C})$  has a basis

$$\{1, x, x^2, x^3, x^4\} / \mathbb{C}$$

Another basis is

$$\{1+i, x+2, ix^2+x, x^3, (1+i)x^4\}$$

Q How about if we regard  $V$  as a vector space /  $\mathbb{R}$ ?

Ans

$$\{1, i, x, ix, x^2, ix^2, x^3, ix^3, x^4, ix^4\}$$

is a basis for  $V / \mathbb{R}$

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Thm Every vector space  $V / \mathbb{F}$  has a basis

(Pf by set theory)

Thm If  $S, S'$  are both bases of  $V$ , then

$S$  and  $S'$  have same cardinality

If  $S$  and  $S'$  are finite, it just means that they have the same number of elements

This cardinality is defined to be  $\dim V$  (dimension)

Thm Let  $\dim V = n$ ,  $S \subseteq V$  be a subset with  $n$  elements.

Then  $S$  is linearly independent  $\Leftrightarrow \text{Span } S = V$

In particular,  $S$  is a basis in this situation.

eg. Are they bases of  $P_2(\mathbb{R})$ ?

$$(1) \{x^2+2x+2, x^2+1, x^2+4x+4\} = S_1$$

$$(2) \{x^2+2x+2, x^2+1, x^2+4x+3\} = S_2$$

Sol (1) Check linear independence:

Suppose

$$a_1(x^2+2x+2) + a_2(x^2+1) + a_3(x^2+4x+4) \equiv 0$$

$$\text{then } (a_1+a_2+a_3)x^2 + (2a_1+4a_3)x + (2a_1+a_2+4a_3) \equiv 0$$

$$\Rightarrow \begin{cases} a_1 + a_2 + a_3 = 0 \\ 2a_1 + 4a_3 = 0 \\ 2a_1 + a_2 + 4a_3 = 0 \end{cases}$$

Gaussian elimination  $\left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 2 & 0 & 4 & 0 \\ 2 & 1 & 4 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & -2 & 2 & 0 \\ 0 & -1 & 2 & 0 \end{array} \right]$

$$\rightarrow \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & -1 & 2 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right]$$

(8)

$$\begin{aligned} \therefore a_3 = 0 &\Rightarrow \begin{cases} a_3 = 0 \\ a_2 = 0 \\ a_1 = 0 \end{cases} \\ a_2 - a_3 = 0 &\Rightarrow \\ a_1 + a_2 + a_3 = 0 &\Rightarrow \end{aligned}$$

$\therefore S_1$  is linearly independent

Note  $\dim P_2(\mathbb{R}) = 3$ ,  $S_1$  has 3 elements

$$\Rightarrow \text{Span } S_1 = P_2(\mathbb{R})$$

$$\Rightarrow S_1 \text{ is a basis of } P_2(\mathbb{R}) \quad \square$$

(2) Suppose  $a_1(x^2+2x+2) + a_2(x^2+1) + a_3(x^2+4x+3) \equiv 0$

Similarly  $\left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 2 & 0 & 4 & 0 \\ 2 & 1 & 4 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$

$a_1, a_2$  are lead/pivot/basic variables  $\leftarrow$  pivot  
 $a_3$  is a free variable  $\leftarrow$  [1] leading 1

The system is consistent and has infinitely many solutions. In particular,  $a_3=1, a_2=1, a_1=-2$  is one of them  $\Rightarrow S_2$  is not lin. indept  $\Rightarrow$  not a basis



# Something about Matrices (Most of the time)

$\mathbb{F} = \mathbb{C}$  or  $\mathbb{R}$

## - Matrix multiplication

$$A \in M_{m \times n}(\mathbb{F}) \quad B \in M_{n \times k}(\mathbb{F})$$

↑  
m rows, n columns

$$AB \in M_{m \times k}(\mathbb{F})$$

## - Gaussian elimination

- Augmented matrix
- elementary row operations (3 types)
- (Reduced) row echelon form

leading 1's

$$\begin{bmatrix} \boxed{1} & 2 & 3 \\ \boxed{11} & 4 & 5 \\ 0 & 1 & 1 \end{bmatrix} \quad \begin{bmatrix} \boxed{1} & \boxed{2} & 3 \\ 0 & \boxed{1} & 1 \\ 0 & 0 & 0 \end{bmatrix} \quad \begin{bmatrix} \boxed{1} & 0 & 2 \\ 0 & \boxed{1} & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

ref?	X	✓	✓
rref?	X	X	✓

• lead/pivot/basic variables, free variables

$$\begin{bmatrix} \boxed{1} & 2 & 3 & 4 & 5 & | & 9 \\ 0 & 0 & \boxed{1} & 6 & 7 & | & 10 \\ 0 & 0 & 0 & \boxed{1} & 8 & | & 11 \end{bmatrix}$$

$x_1, x_3, x_4$  pivot  
 $x_2, x_5$  free

• number of solutions

$$\begin{bmatrix} 1 & 1 & 2 & | & 1 \\ 0 & 1 & -1 & | & 2 \\ 0 & 0 & 0 & | & 3 \end{bmatrix} \quad \begin{bmatrix} \boxed{1} & 1 & 2 & | & 1 \\ 0 & \boxed{1} & -1 & | & 2 \\ 0 & 0 & \boxed{1} & | & 3 \end{bmatrix} \quad \begin{bmatrix} \boxed{1} & 1 & 2 & | & 1 \\ 0 & \boxed{1} & -1 & | & 2 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

no solution      unique solution *no free variable*      infinitely many solutions

• Express solutions in parametric form

eg.  $\textcircled{*} (x, y, z) = (-1, 2, 0) + t(-3, 1, 1)$

• Finding inverse of a square matrix

$$\underbrace{\begin{bmatrix} 1 & 2 & 3 & | & 1 & 0 & 0 \\ 0 & 3 & 4 & | & 0 & 1 & 0 \\ 2 & 5 & 7 & | & 0 & 0 & 1 \end{bmatrix}}_A \sim \begin{bmatrix} 1 & 0 & 0 & | & -1 & -1 & 1 \\ 0 & 1 & 0 & | & -8 & -1 & 4 \\ 0 & 0 & 1 & | & 6 & 1 & -3 \end{bmatrix}$$

$A^{-1}$

The following are equivalent

- For  $A \in M_{n \times n}(\mathbb{F})$ , TFAE

- ① A is invertible
- ②  $\text{rref}(A) = I_n$
- ③ Each diagonal entry of any ref of A is non-zero
- ④  $A\vec{x} = \vec{b}$  has unique solution for any  $\vec{b} \in \mathbb{F}^n$
- ⑤  $\text{rank } A = n$
- ⑥  $\text{nullity } A = 0$
- ⑦  $\det A \neq 0$

## Linear transformations

Def Let  $V, W$  be vector space /  $\mathbb{F}$ .

A map  $T: V \rightarrow W$  is called a linear transformation if  $\forall x, y \in V, a \in \mathbb{F}$

- $T(x+y) = T(x) + T(y)$
- $T(ax) = aT(x)$

eg  $A \in M_{m \times n}(\mathbb{F})$ . Then  $T: \mathbb{F}^n \rightarrow \mathbb{F}^m$  defined by  $T(x) = Ax$  is linear

### Properties of a linear transformation $T: V \rightarrow W$

$$1. \quad T(\vec{0}) = \vec{0}$$

$\uparrow$  in  $V$        $\uparrow$  in  $W$

$$2. \quad T\left(\sum_{i=1}^k a_i x_i\right) = \sum_{i=1}^k a_i T(x_i)$$

for any  $x_1, x_2, \dots, x_k \in V, a_1, a_2, \dots, a_k \in \mathbb{F}$

(10)

Def let  $T: V \rightarrow W$  be a linear transformation

Define

null space (kernel)  $N(T) = \{x \in V \mid T(x) = \vec{0}\}$

range (image)  $R(T) = \{T(x) \mid x \in V\}$

Note  $N(T) \subseteq V, R(T) \subseteq W$  are linear subspaces.

Define

nullity  $(T) = \dim N(T)$   $\uparrow$  re vector subspaces

rank  $(T) = \dim R(T)$

Properties For  $T: V \rightarrow W$

$T$  is one-to-one  $\Leftrightarrow N(T) = \{0\}$

$\Leftrightarrow$  nullity  $(T) = 0$

$T$  is onto  $\Leftrightarrow R(T) = W$

$\Leftrightarrow$  rank  $(T) = \dim W$  (if  $\dim W < \infty$ )

Dimension theorem: If  $\dim V < \infty$

$\text{nullity}(T) + \text{rank}(T) = \dim V$

## Normed Space ( $\mathbb{F} = \mathbb{R}$ or $\mathbb{C}$ )

Defn Let  $X$  be a vector space /  $\mathbb{F}$

A norm on  $X$  is a function

$$\|\cdot\| : X \rightarrow \mathbb{R}$$

such that  $\forall x, y \in X, \alpha \in \mathbb{F}$

N1.  $\|x\| \geq 0$

N2.  $\|x\| = 0 \iff x = \vec{0}$

N3.  $\|\alpha x\| = |\alpha| \|x\|$   $|\alpha| =$  absolute value if  $\mathbb{F} = \mathbb{R}$   
modulus if  $\mathbb{F} = \mathbb{C}$

N4.  $\|x + y\| \leq \|x\| + \|y\|$  Triangle inequality

$(X, \|\cdot\|)$  is called a normed space  
or simply  $X$

Proposition A normed space  $X$  is also a metric space with metric

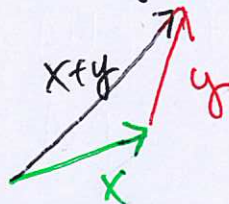
$$d(x, y) = \|x - y\|$$

Pf Check the conditions for metric space

M1:  $d(x, y) = \|x - y\| \geq 0$  by N1

M2:  $d(x, y) = 0 \iff \|x - y\| = 0$   
 $\iff x - y = \vec{0}$  by N2  
 $\iff x = y$

M3:  $d(x, y) = \|x - y\|$   
 $= \|(-1)(y - x)\|$   
 $= |-1| \|y - x\|$  by N3  
 $= \|y - x\| = d(y, x)$



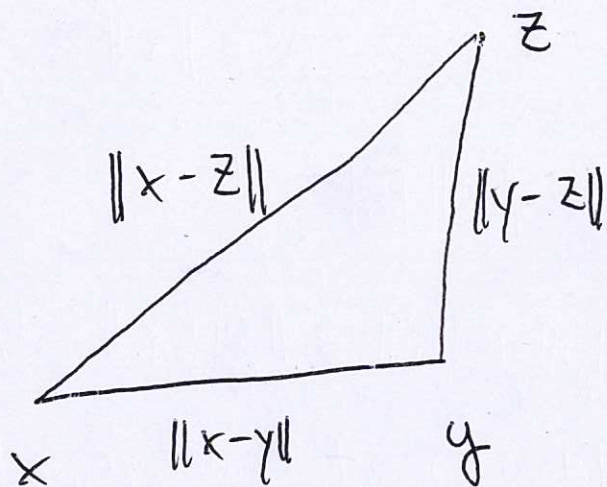
$$M4: d(x, y) + d(y, z)$$

$$= \|x - y\| + \|y - z\|$$

$$\geq \|(x - y) + (y - z)\| \quad \text{by N4}$$

$$= \|x - z\|$$

$$= d(x, z)$$



Rmk If  $X$  is a normed space, then

$\|\cdot\|: X \rightarrow \mathbb{R}$  is a continuous function

Example of normed space

①  $\mathbb{R}^n$ , with norm

$$\|x\| = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$

$\mathbb{C}^n$ , with norm

$$\|z\| = \sqrt{|z_1|^2 + |z_2|^2 + \dots + |z_n|^2}$$

$$z, \bar{z} = |z|^2$$

N1, N2, N3 Easy to verify

N4 a little bit harder

eg 2  $C[0,1]$  with norm defined by

$$\|f\| = \max_{0 \leq x \leq 1} |f(x)| \quad (F = \mathbb{R})$$

Note  $\|f\|$  is well-defined because of

Extreme value theorem,

If  $g(x)$  is continuous on a closed and bounded interval, then  $g(x)$  has maximum and minimum

Verify that  $\|\cdot\|$  is a norm

Sol: Check

N1: For any  $f \in C[0,1]$ ,  $x \in [0,1]$

$$|f(x)| \geq 0 \Rightarrow \|f\| = \max_{0 \leq x \leq 1} |f(x)| \geq 0$$

N2:

$$\|f\| = 0 \Leftrightarrow \max_{0 \leq x \leq 1} |f(x)| = 0$$

$$\Leftrightarrow 0 \leq |f(x)| \leq 0 \text{ for any } 0 \leq x \leq 1$$

$$\Leftrightarrow f(x) = 0 \text{ for any } 0 \leq x \leq 1$$

$$\Leftrightarrow f = \vec{0}, \text{ the zero function}$$

N3:

$$\|\alpha f\| = \max_{0 \leq x \leq 1} |(\alpha f)(x)|$$

$$= \max_{0 \leq x \leq 1} |\alpha(f(x))|$$

$$= \max_{0 \leq x \leq 1} |\alpha| |f(x)|$$

$$= |\alpha| \max_{0 \leq x \leq 1} |f(x)|$$

$$= |\alpha| \|f\|$$

N4: Let  $f, g \in C[0, 1]$

Suppose  $x \in [0, 1]$

$$|(f+g)(x)| = |f(x) + g(x)|$$

Triangle inequality  
for real numbers  $\leq |f(x)| + |g(x)|$

$$\leq \|f\| + \|g\|$$

$$\Rightarrow \max_{0 \leq x \leq 1} |(f+g)(x)| \leq \|f\| + \|g\|$$

$$\Rightarrow \|f+g\| \leq \|f\| + \|g\|$$

N1, N2, N3, N4 ✓

$$\Rightarrow \|f\| = \max_{0 \leq x \leq 1} |f(x)| \text{ is a norm}$$

Q Let  $C(\mathbb{R})$  be the vector space of all continuous function on  $\mathbb{R}$

Does  $\|f\| = \max_{x \in \mathbb{R}} |f(x)|$  define a norm on  $C(\mathbb{R})$ ?

A No: Problem is  $\|f\|$  may not be well-defined

$f(x) = x \quad \forall x \in \mathbb{R}$ ,  $|f(x)|$  has no maximum

Q How about on  $C(0, 1)$  = vector space of all continuous function on  $(0, 1)$

A No: Same problem:

eg.  $f(x) = \frac{1}{x}$   $|f(x)|$  is unbounded

Modification:

eg let  $A \subseteq \mathbb{R}$  be a subset

$B(A)$  = the vector space of all  
bounded functions defined on  $A$

$$= \left\{ f: A \rightarrow \mathbb{R} : \exists M > 0 \text{ such that } |f(x)| \leq M \forall x \in A \right\}$$

Then

$$\|f\| = \sup_{x \in A} |f(x)|$$

defines a norm on  $B(A)$

Rmk  $\max_{x \in A} |f(x)|$  may not exist: eg.  $f(x) = 1 - \frac{1}{x}$   
 $A = [1, \infty)$

